			··	
L Number	Hits	Search Text	DB	Time stamp
1	205	(fork near3 lift) and (wheel near3 bear\$4)	USPAT;	2003/04/16 11:17
			EPO; JPO;	1
			DERWENT;	•
	55.64.6	2 264 2 2 44	IBM_TDB	2002/04/16 12 10
2	75616	load\$4 near3 bear\$4	USPAT;	2003/04/16 11:18
			EPO; JPO;	
			DERWENT;	
		//6	IBM_TDB	2002/04/16 11 21
3	66	1 ' '	USPAT;	2003/04/16 11:21
		and (load\$4 near3 bear\$4)	EPO; JPO; DERWENT;	
			IBM TDB	
4	24408	wheel near3 load\$4	USPAT;	2003/04/16 11:43
	24400	wheel hears roady4	EPO; JPO;	2003/04/10 11:43
			DERWENT;	
			IBM TDB	
6	26834	((speed or velocity)near3 rotation)and	USPAT;	2003/04/16 11:27
		(stabi\$8 or tip\$9)	EPO; JPO;	
		(2000040 00 0-241)	DERWENT;	
			IBM TDB	
7	19021	((speed or velocity)near3 rotation)and	USPAT;	2003/04/16 11:48
<u> </u>		(stabi\$8 or tipping)	EPO; JPO;	
{			DERWENT;	
i			IBM TDB	
8	0	((((fork near3 lift)and (wheel near3	USPĀT;	2003/04/16 11:25
		bear\$4)) and (load\$4 near3 bear\$4)) and	EPO; JPO;	
		(wheel near3 load\$4)) and (((speed or	DERWENT;	
		velocity)near3 rotation)and (stabi\$8 or	IBM_TDB	
		tipping))		l
9	1	((fork near3 lift)and (wheel near3 bear\$4))	USPAT;	2003/04/16 11:25
		and (((speed or velocity)near3 rotation)and	EPO; JPO;	
		(stabi\$8 or tipping))	DERWENT;	
			IBM_TDB	
11	123119	(speed or velocity)near3 rotation	USPAT;	2003/04/16 11:29
			EPO; JPO;	
i			DERWENT;	
1,2		////fowly many? lift\and /haal many?	IBM_TDB	2002/04/16 11:20
12	1	((((fork near3 lift)and (wheel near3 bear\$4)) and (load\$4 near3 bear\$4)) and	USPAT; EPO; JPO;	2003/04/16 11:28
		(wheel near3 load\$4)) and ((speed or	DERWENT;	
		velocity)near3 rotation)	IBM TDB	
13	729743		USPAT;	2003/04/16 11:32
	, 25, 15	beautitey	EPO; JPO;	2003, 01, 10 11:32
			DERWENT;	
			IBM_TDB	
14	18	(((fork near3 lift)and (wheel near3 bear\$4))	USPAT;	2003/04/16 11:29
İ		and (load\$4 near3 bear\$4)) and stability	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
15	249362	(speed or velocity)same rotation	USPAT;	2003/04/16 11:29
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
16	5	(((fork near3 lift)and (wheel near3 bear\$4))	USPAT;	2003/04/16 11:31
		and (load\$4 near3 bear\$4)) and ((speed or	EPO; JPO;	
		velocity)same rotation)	DERWENT;	
, ,	212	h	IBM_TDB	2002/04/25 12 25
17	313	wheel near3 load near3 sensor	USPAT;	2003/04/16 11:31
i i			EPO; JPO;	
			DERWENT; IBM TDB	
18	22	(load\$4 near3 bear\$4) and (wheel near3 load	USPAT;	2003/04/16 11:32
-~	22	near3 sensor)	EPO; JPO;	2003/04/10 11:32
			DERWENT;	
			IBM TDB	
19	1	((fork near3 lift)and (wheel near3 bear\$4))	USPAT;	2003/04/16 11:32
	_	and ((load\$4 near3 bear\$4) and (wheel near3	EPO; JPO;	, 5-, 25 11.52
1		load near3 sensor))	DERWENT;	
		,		
			IBM TDB	

1271	(fork near3 lift)and stability	USPAT; EPO; JPO; DERWENT;	2003/04/16 11:33
1	((load\$4 near3 bear\$4) and (wheel near3 load near3 sensor)) and ((fork near3 lift)and stability)	IBM_TDB USPAT; EPO; JPO; DERWENT;	2003/04/16 11:33
4	(wheel near3 load near3 sensor) and ((fork near3 lift)and stability)	USPAT; EPO; JPO; DERWENT;	2003/04/16 11:33
45	(((fork near3 lift)and (wheel near3 bear\$4)) and (load\$4 near3 bear\$4)) and (wheel near3 load\$4)	USPAT; EPO; JPO; DERWENT;	2003/04/16 11:35
381	wheel near3 load\$4 near3 sensor	USPAT; EPO; JPO; DERWENT;	2003/04/16 11:44
1	((fork near3 lift)and stability) and ((load\$4 near3 bear\$4) and (wheel near3 load\$4 near3 sensor))	USPAT; EPO; JPO; DERWENT;	2003/04/16 11:44
29	(load\$4 near3 bear\$4) and (wheel near3 load\$4 near3 sensor)	USPAT; EPO; JPO; DERWENT;	2003/04/16 11:45
23835	((speed or velocity)near3 rotation)and (stabi\$8 or tipping or tilt\$4)	USPAT; EPO; JPO; DERWENT;	2003/04/16 11:57
3	<pre>((fork near3 lift)and (wheel near3 bear\$4)) and (((speed or velocity)near3 rotation)and (stabi\$8 or tipping or tilt\$4))</pre>	USPAT; EPO; JPO; DERWENT;	2003/04/16 11:50
24	((fork near3 lift)and stability) and (((speed or velocity)near3 rotation)and (stabi\$8 or tipping or tilt\$4))	USPAT; EPO; JPO; DERWENT;	2003/04/16 11:50
2502	(((speed or velocity)near3 rotation)same wheel)and (stabi\$8 or tipping or tilt\$4)	USPAT; EPO; JPO; DERWENT;	2003/04/16 11:58
7	<pre>((fork near3 lift)and stability) and ((((speed or velocity)near3 rotation)same wheel)and (stabi\$8 or tipping or tilt\$4))</pre>	USPAT; EPO; JPO; DERWENT;	2003/04/16 12:00
11947	<pre>(wheel or tyre or tire)near3 (rotation\$5 near3 (velocity or speed))</pre>	USPAT; EPO; JPO; DERWENT;	2003/04/16 12:02
0	<pre>and (load\$4 near3 bear\$4)) and ((wheel or tyre or tire)near3 (rotation\$5 near3</pre>	USPAT; EPO; JPO; DERWENT;	2003/04/16 12:02
1998		USPAT; EPO; JPO; DERWENT;	2003/04/16 12:03
0	<pre>((fork near3 lift)and (wheel near3 bear\$4)) and ((wheel or tyre or tire)near3 (rotation\$5 same( velocity or speed)))</pre>	USPAT; EPO; JPO; DERWENT;	2003/04/16 12:03
7	<pre>((fork near3 lift)and stability) and ((wheel or tyre or tire)near3 (rotation\$5 near3 (velocity or speed)))</pre>	USPAT; EPO; JPO; DERWENT;	2003/04/16 12:03
	1 4 45 381 1 29 23835 3 24 2502 7 11947 0 1998	((load\$4 near3 bear\$4) and (wheel near3 load near3 sensor)) and ((fork near3 lift)and stability)  ((wheel near3 load near3 sensor) and ((fork near3 lift)and stability)  (((fork near3 lift)and (wheel near3 bear\$4)) and (load\$4 near3 bear\$4)) and (wheel near3 load\$4)  (((load\$4 near3 lift)and stability) and ((load\$4 near3 bear\$4)) and (wheel near3 load\$4 near3 sensor)  ((speed or velocity)near3 rotation)and (stabis\$8 or tipping or tilt\$4)  ((fork near3 lift)and (wheel near3 bear\$4)) and ((speed or velocity)near3 rotation)and (stabis\$8 or tipping or tilt\$4))  ((fork near3 lift)and stability) and (((speed or velocity)near3 rotation)and (stabis\$8 or tipping or tilt\$4))  (((speed or velocity)near3 rotation)and (stabis\$8 or tipping or tilt\$4))  (((speed or velocity)near3 rotation)same wheel)and (stabis\$8 or tipping or tilt\$4))  (((speed or velocity)near3 rotation)same wheel)and (stabis\$8 or tipping or tilt\$4))  (((speed or velocity)near3 rotation)same wheel)and (stabis\$8 or tipping or tilt\$4))  (((speed or velocity)near3 rotation)same wheel)and (stabis\$8 or tipping or tilt\$4))  (((fork near3 lift)and stability) and (((speed or velocity)near3 rotation)same wheel)and (stabis\$8 or tipping or tilt\$4))  (((fork near3 lift)and stability) and ((wheel or tyre or tire)near3 (rotation\$5 near3 (velocity or speed)))  (((fork near3 lift)and (wheel near3 bear\$4)) and (load\$4 near3 bear\$4)) and ((wheel or tyre or tire)near3 (rotation\$5 same( velocity or speed)))  ((fork near3 lift)and (wheel near3 bear\$4)) and ((wheel or tyre or tire)near3 (rotation\$5 same( velocity or speed)))  (((fork near3 lift)and stability) and ((wheel or tyre or tire)near3 (rotation\$5 same( velocity or speed)))	1 ((load\$4 near3 bear\$4) and (wheel near3 load near3 sensor)) and ((fork near3 lift) and stability) 4 (wheel near3 load near3 sensor) and ((fork near3 lift) and stability) 4 (wheel near3 lift) and (wheel near3 bear\$4)) and (load\$4 near3 bear\$4)) and (wheel near3 load\$4) 381 wheel near3 load\$4 near3 sensor 381 ((fork near3 lift) and stability) and ((fork near3 lift) and stability) and ((load\$4 near3 bear\$4)) and (wheel near3 load\$4 near3 sensor 382 ((fork near3 lift) and stability) and ((load\$4 near3 bear\$4)) and (wheel near3 load\$4 near3 sensor)) 583 ((speed or velocity) near3 rotation) and (stabi\$8 or tipping or tilt\$4) 584 ((fork near3 lift) and (wheel near3 lift) and ((speed or velocity) near3 rotation) and (stabi\$8 or tipping or tilt\$4) 585 ((speed or velocity) near3 rotation) and (stabi\$8 or tipping or tilt\$4) 586 ((speed or velocity) near3 rotation) and (stabi\$8 or tipping or tilt\$4) 587 ((speed or velocity) near3 rotation) and ((stabi\$8 or tipping or tilt\$4) 587 ((speed or velocity) near3 rotation) and ((stabi\$8 or tipping or tilt\$4) 587 ((speed or velocity) near3 rotation) and ((stabi\$8 or tipping or tilt\$4) 588 ((speed or velocity) near3 rotation) and ((stabi\$8 or tipping or tilt\$4) 587 ((speed or velocity) near3 rotation) and ((stabi\$8 or tipping or tilt\$4) 587 ((speed or velocity) near3 rotation) same wheel) and (stabi\$8 or tipping or tilt\$4) 587 ((speed or velocity) near3 rotation) same wheel) and (stabi\$8 or tipping or tilt\$4) 587 ((speed or velocity) near3 rotation) same wheel) and (stabi\$8 or tipping or tilt\$4) 588 ((speed or velocity) near3 rotation) same wheel) and (stabi\$8 or tipping or tilt\$4) 580 ((speed or velocity) near3 (rotation\$5 near3 (velocity or speed)) 580 ((speed or velocity) near3 (rotation\$5 near3 (velocity or speed)) 580 ((speed or velocity) near3 (rotation\$5 near3 (velocity or speed)) 580 ((speed or velocity) near3 (rotation\$5 near3 (velocity or speed)) 580 ((speed or velocity) near3 (rotation\$5 near3 (velocity or speed)) 580 ((speed or velocity) near3 (rotation\$5 near3 (veloci

L Number	Hits	Search Text	DB	Time stamp
19	251	fork near3 lift\$3 and wheel near5 bear\$3	USPAT;	2003/04/16 08:13
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
20	74101	load\$3 near3 bear\$3	USPAT;	2003/04/16 08:13
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
	70	(factor and lifeth) and wheel moors bearth) and (loadf) noors	IBM_TDB USPAT;	2003/04/16 08:13
21	76	(fork near3 lift\$3 and wheel near5 bear\$3) and (load\$3 near3	US-PGPUB:	2003/04/10 00.13
		bear\$3)	EPO; JPO;	
			DERWENT:	
			IBM TDB	
23	5	(((fork near3 lift\$3 and wheel near5 bear\$3) and (load\$3 near3	USPAT;	2003/04/16 08:14
		bear\$3)) and (wheel tyre tire) near3 (rotation\$5 velocity	US-PGPUB;	
		speed)) and (stabli\$8 tip\$3)	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
22	20	((fork near3 lift\$3 and wheel near5 bear\$3) and (load\$3 near3	USPAT;	2003/04/16 08:18
		bear\$3)) and (wheel tyre tire) near3 (rotation\$5 velocity speed)	US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
i i		l	LIBM TDB	l